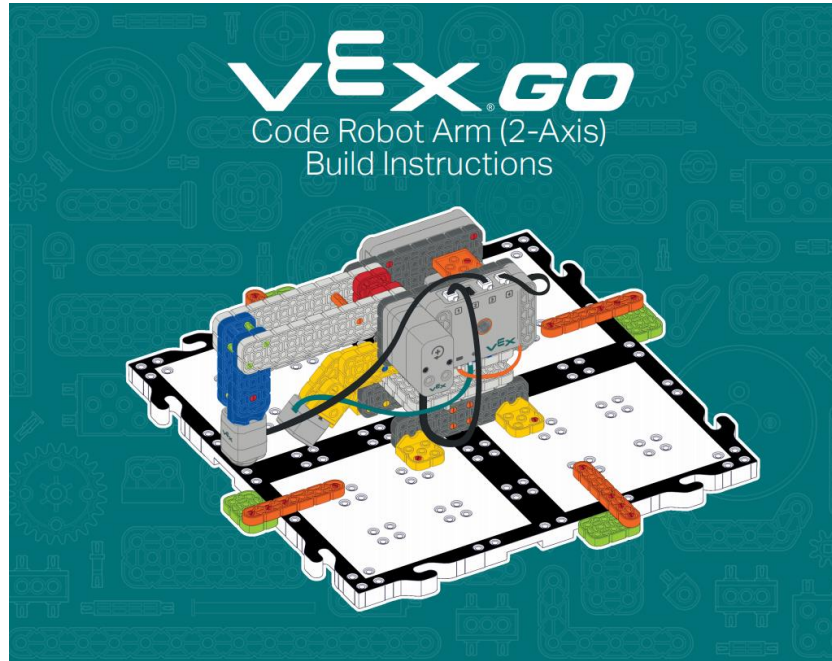


Robot Arm

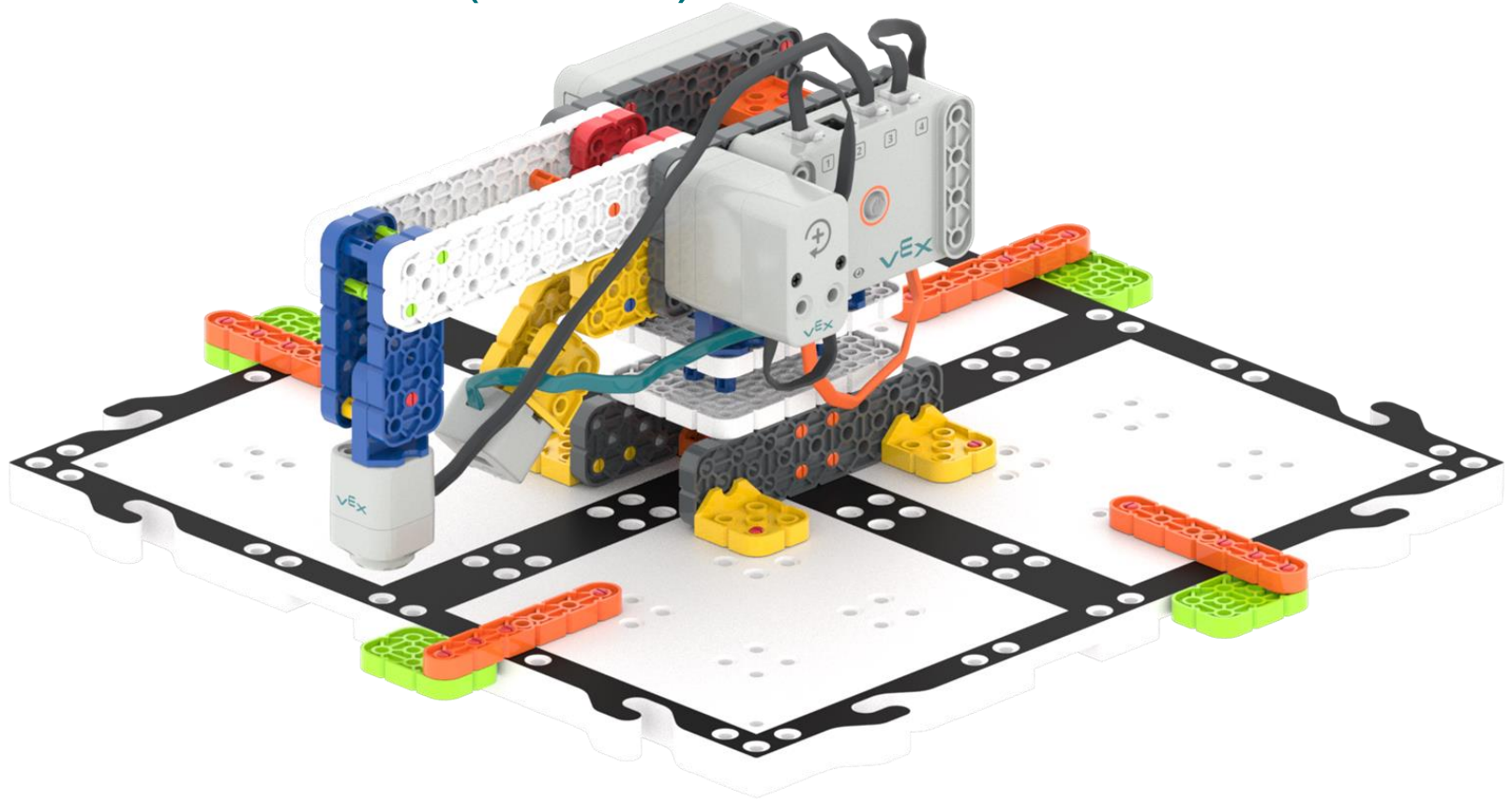
Lab 4

Baue den Code Robot Arm (2-Axis)

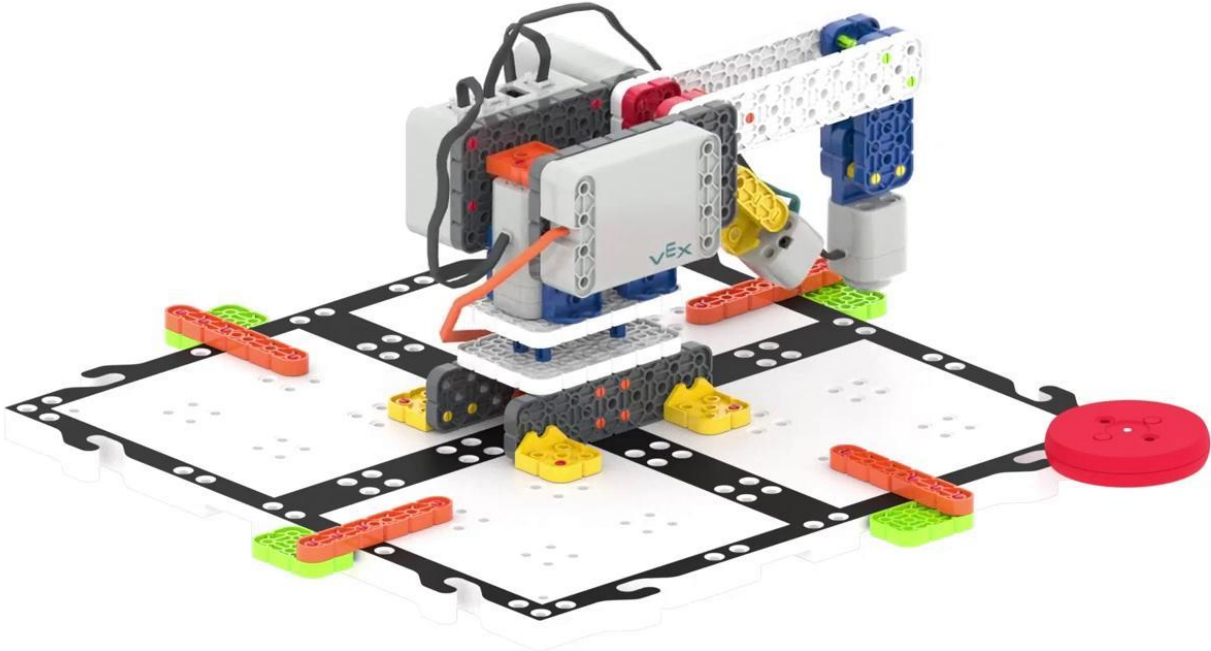


siehe Bauanleitungen: [Code Robot Arm \(2-Axis\)](#)

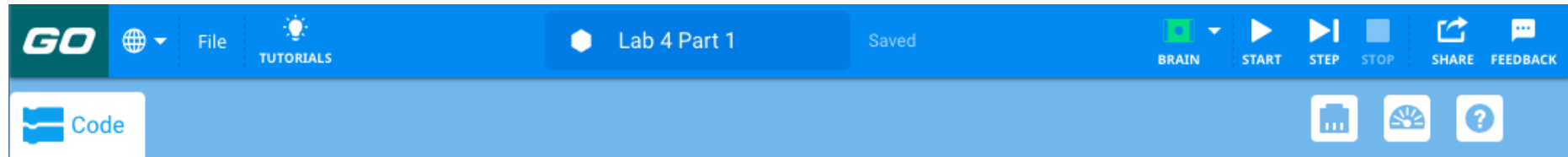
Code Robot Arm (2-Axis)



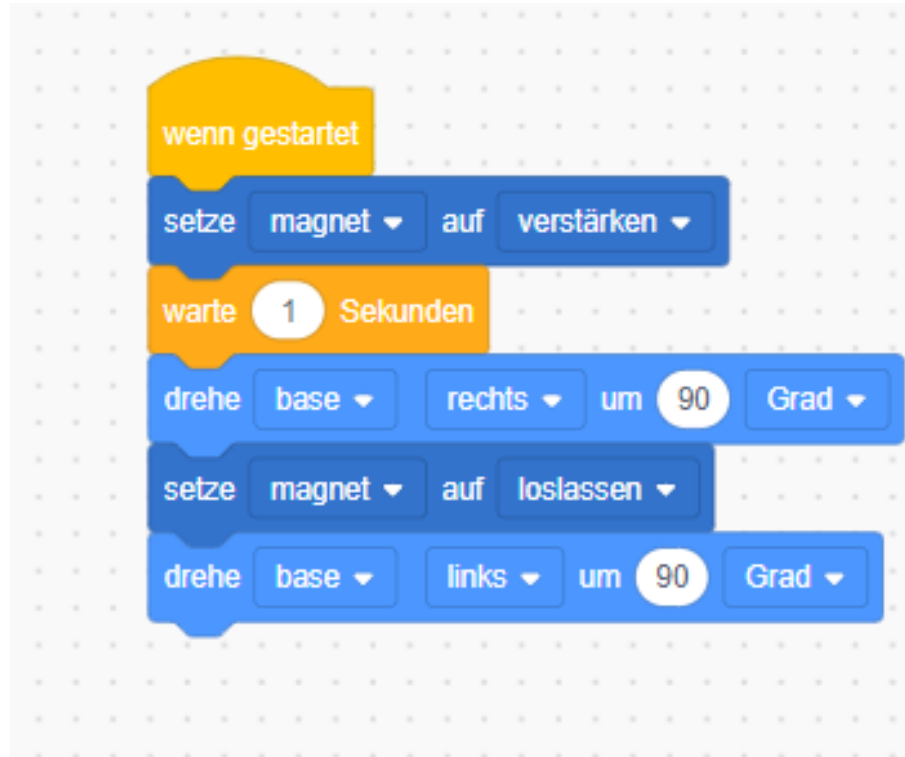
Roboterarm mit Disk



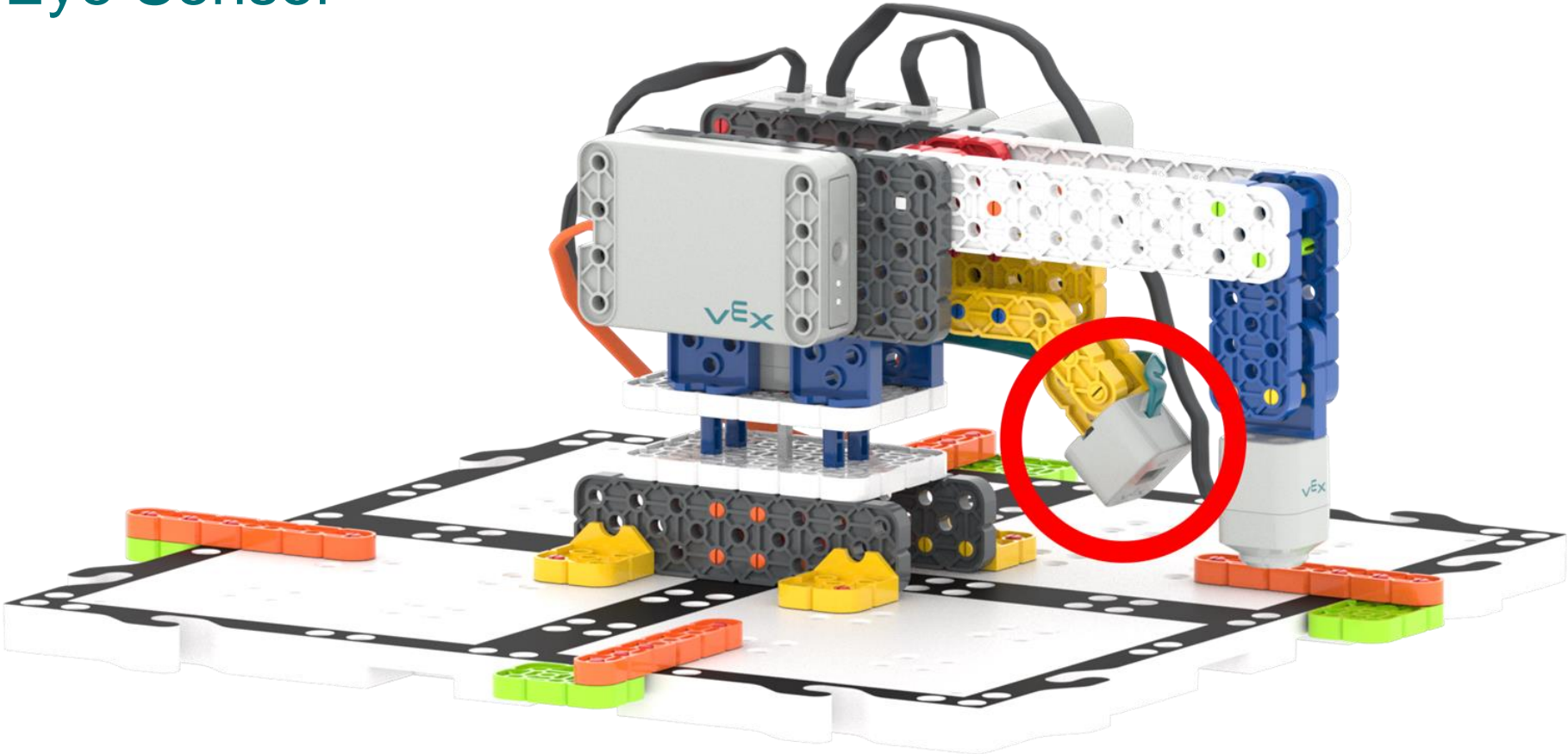
Gib Deinem Projekt einen neuen Namen



Lab 3 Teil 2 Lösung



Eye Sensor



Optischer Sensor

Optischer Sensor

setze Farblicht an ▼

setze Lichtstärke von Auge auf 50 %

Auge hat Objekt gefunden?

Auge erkennt rot ▼ ?

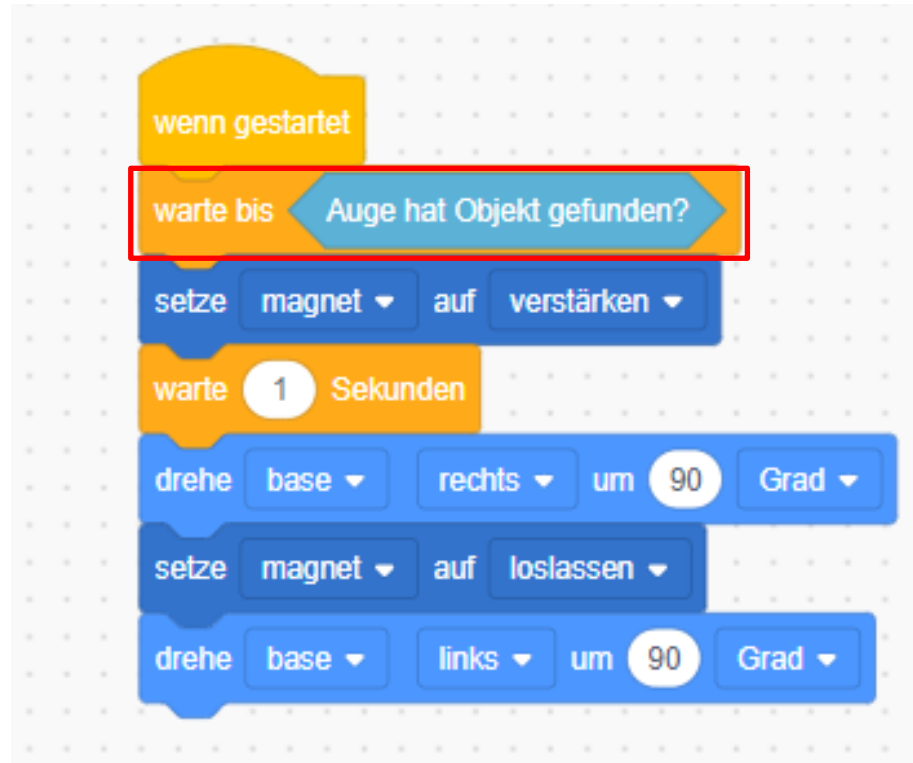
Helligkeit Auge in %

Farbton Auge in Grad

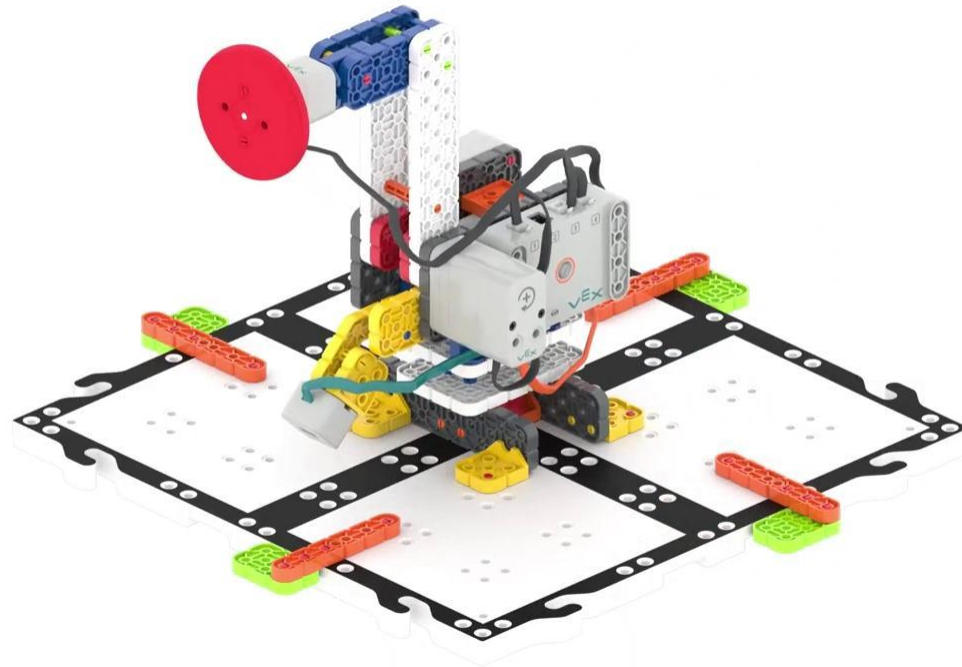
Variables
Meine Blöcke
Kommentare



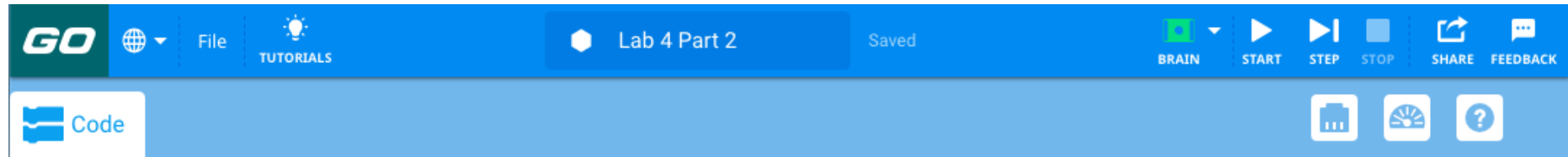
Füge <Auge hat ein Objekt gefunden> in einen [warte bis]-Block



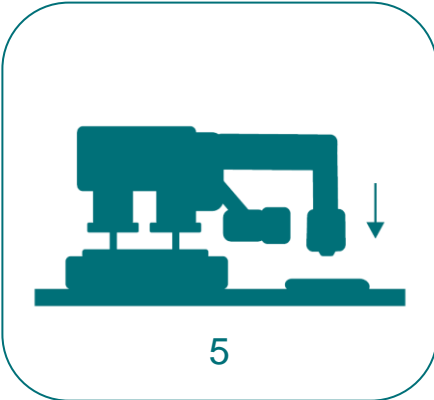
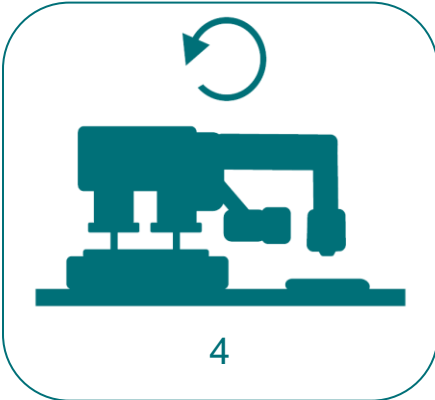
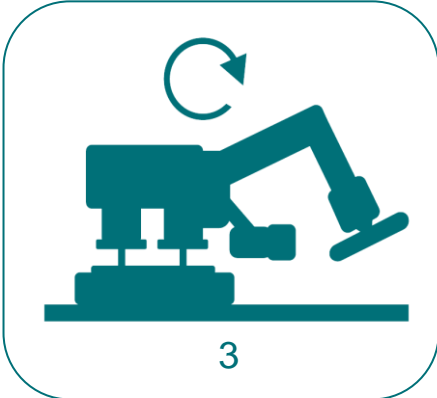
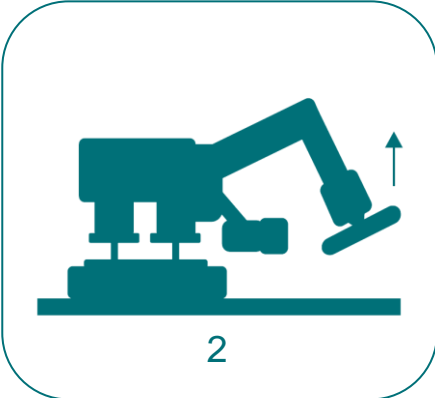
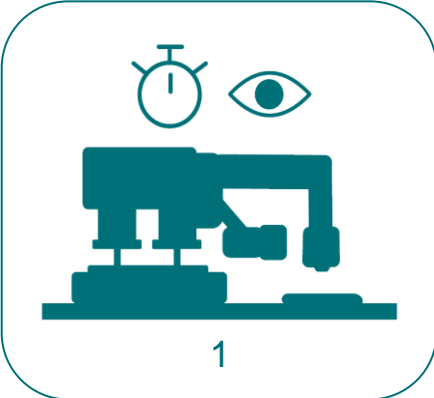
Lab 4 Teil 2



Gib Deinem Projekt einen neuen Namen



Dein Robotarm sollte...



Lab 4 Teil 2 - Lösung

