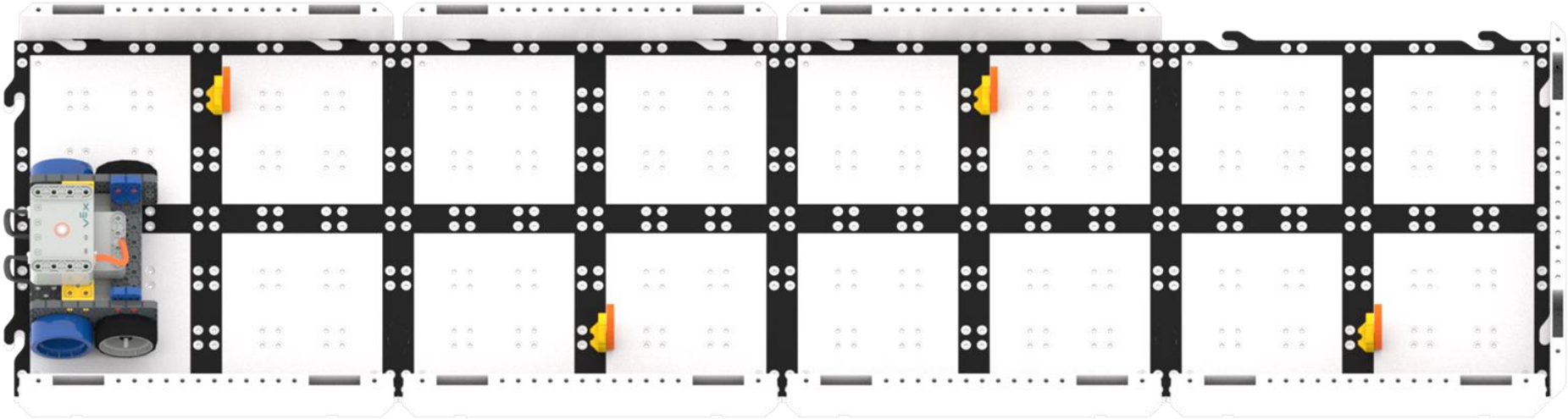
Code Base

Lab 2

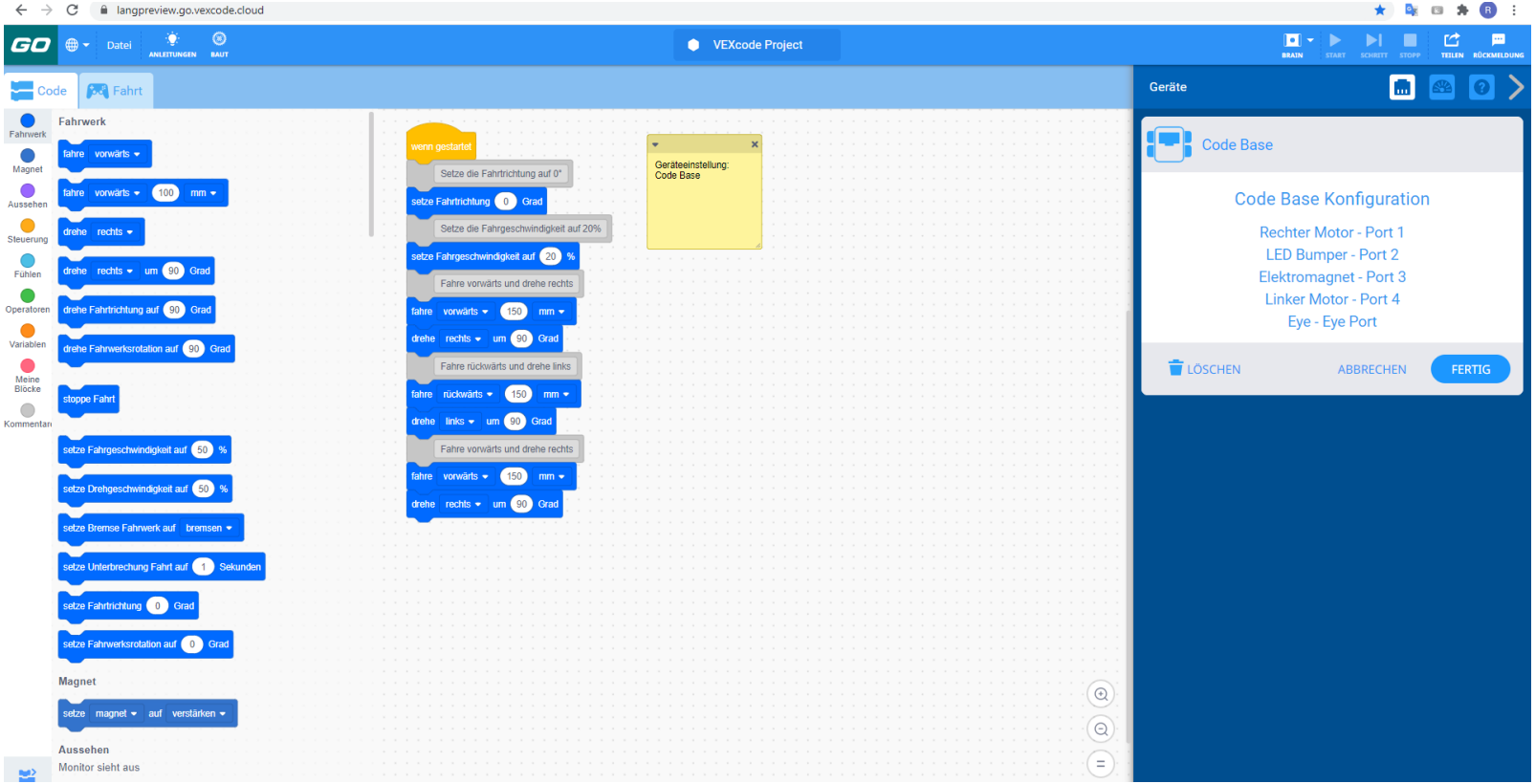
Baue den VEX GO Code Base Roboter

siehe Bauanleitungen: Code Base

Slalomkurs Aufbau

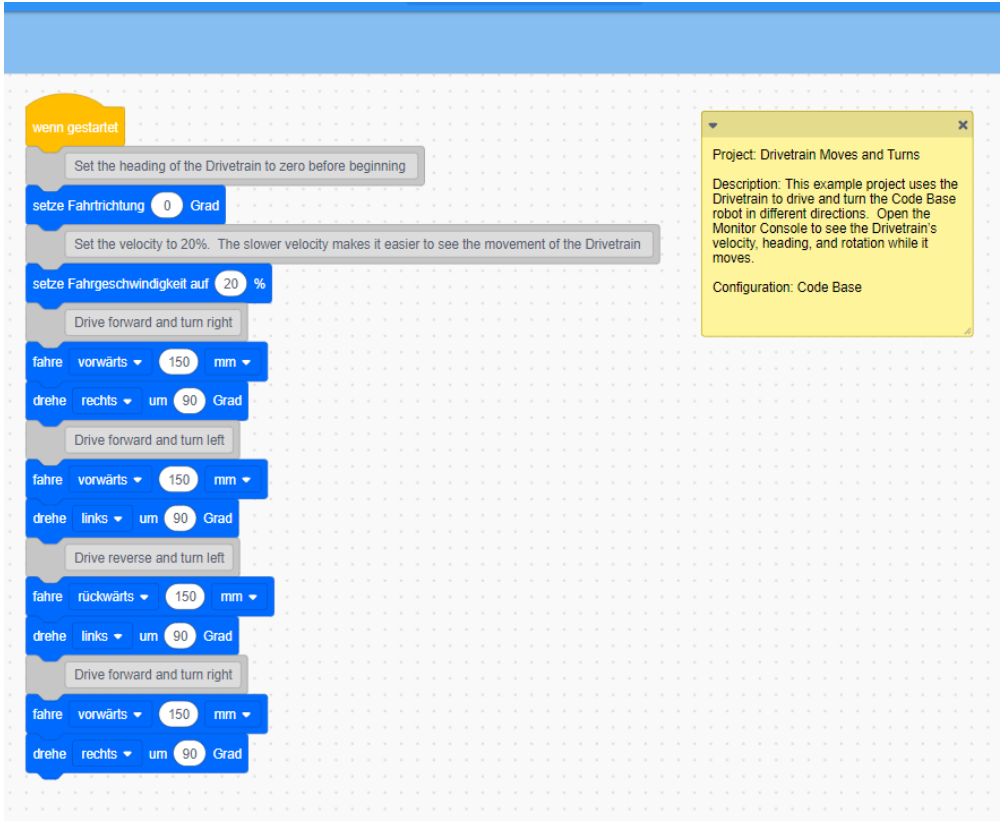


Code Base - Drivetrain “Fahren und Drehen”

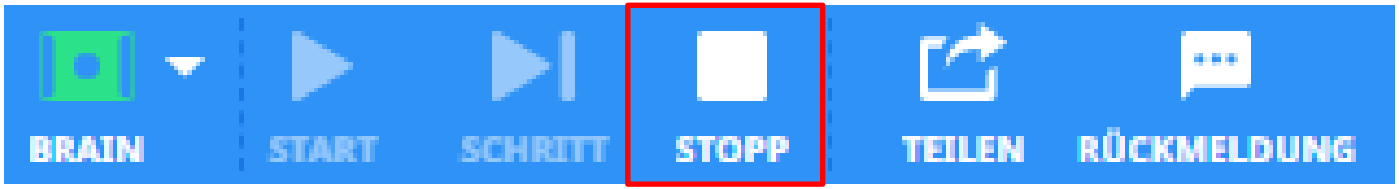


Beispiele öffnen

Beispiel: Drivetrain Moves and Turns



Project stoppen



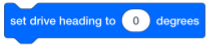
Eingaben ändern

Hife Fenster

Hilfe

Set drive heading

Sets the Drivetrain's Gyro heading value. The Gyro Sensor is built into the VEX GO Brain.

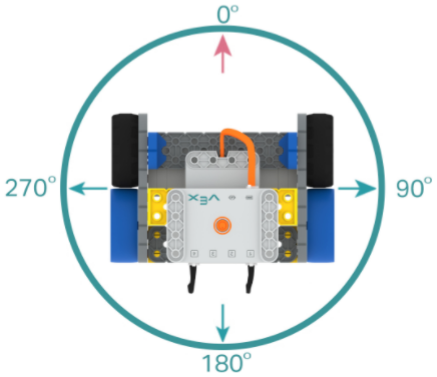


How To Use

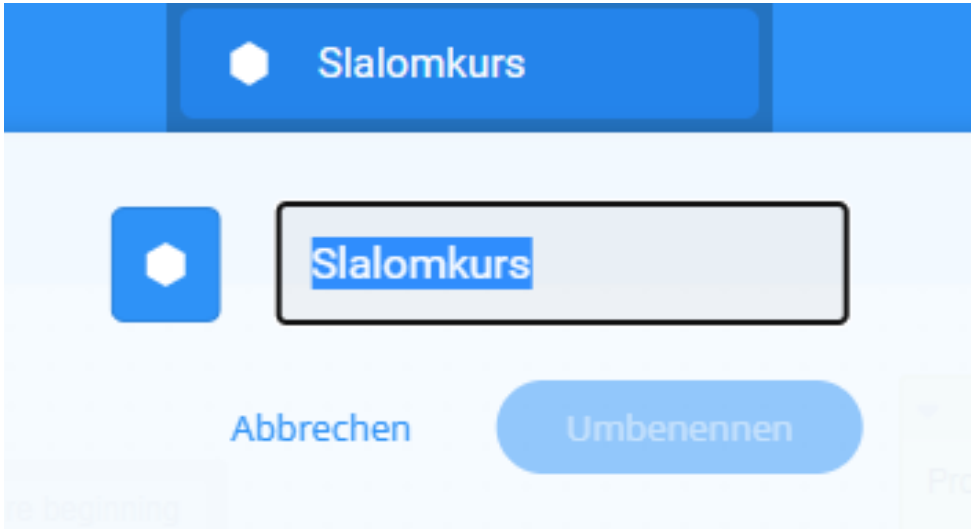
The **Set drive heading** block accepts a range of 0 to 359.99 degrees.

The **Set drive heading** block can accept integers or reporter blocks.

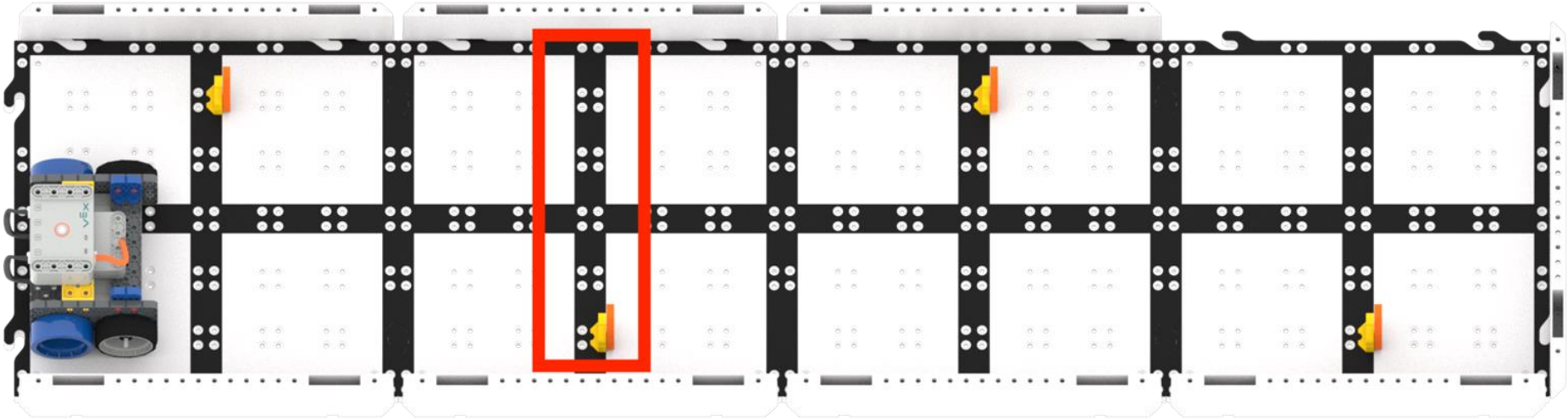
The **Set drive heading** block can be used to set the Drivetrain's position to any given clockwise heading as shown in the image below.



Projekt einen Namen geben



Am zweiten Tor anhalten!



Project stoppen